



A NOVEL NON-RIGID REGISTRATION ALGORITHM FOR ZEBRAFISH LARVAL IMAGES

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OVERVIEW

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 - Minimum Weight Bipartite Graph Matching
 - Diffeomorphic Demons Method
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- CONCLUSION & FUTURE SCOPE

BACKGROUND

- Precise mapping of gene expression profiles, neuronal types and connections during vertebrate brain development
- Zebrafish (*Danio rerio*) as evolved as an ideal model organism for bio-imaging approaches in vertebrates
- ViBE-Z fails to achieve accurate registration due to false landmark detection in low resolution image – and local under/over exposed image of the larvae

PROPOSED METHODOLOGY

- Coarse affine registration using the LBFGS algorithm is applied first on the moving dataset
- The coarsely registered moving image and the reference image are divided into a union of overlapping patches
- Minimum weight bipartite graph matching algorithm is employed to find the correspondence between the two sets of patches
- The corresponding patches are then registered using the diffeomorphic demons method with proper intra-patch regularization
- Inter-patch regularization is imposed through a composite transformation obtained from the adjacent transformation fields

Coarse Registration

- $M_p(x, y, z)$ denotes the p th voxel in the moving image M and $F_p(x, y, z)$ be the p th voxel in the fixed image F
- The affine transformation on $M_p(x, y, z)$ yields $M'_p(x', y', z')$ therefore, $M'_p(x', y', z') = T(M_p(x, y, z))$
- The L-BFGS algorithm is applied to optimize the cost function $\sum_p \|I(F_p) - I(M'_p)\|^2$ to obtain the affine transformation parameters

Patch Correspondence using Minimum Weight Bipartite Matching

- The coarsely registered moving image M' and the fixed image F are divided into n overlapping volumetric patches
- A bipartite graph is represented by $G = (V1 \cup V2, E)$ with two disjoint vertex sets $V1$ and $V2$ and the edge set E (edges exist only across the vertex sets)
- The centroids of the coarsely registered moving image patches $M'_{1c}, M'_{2c}, \dots, M'_{nc}$ and that of the fixed image patches $F_{1c}, F_{2c}, \dots, F_{nc}$ constitute the two disjoint vertex sets. For the present problem, $|V1| = |V2| = n$
- Mean of the differences in the intensity values of the constituent pixels in two patches is assigned as the weight of the edge between the respective patch centroids.
- The weight of the edges is given by $W(M'_i, F_j)$,

$$W(M'_i, F_j) = \frac{\sum_p |I(F_{jp}) - I(M'_{ip})|^2}{p}$$
- The Kuhn-Munkres algorithm is applied to solve the minimum weight bipartite matching problem. This algorithm yields an optimal match set $\Gamma(M'_i, F_{m(i)})$, $i = 1, 2, \dots, n$

Patch Registration using Diffeomorphic Demons

- The corresponding patches are registered using diffeomorphic demons minimizing the following energy function.

$$E(T'_i) = \frac{Sim(I(F_{mi}), I(T'_i(M'_i)))}{\alpha_1^2} + \frac{Reg(T'_i)}{\alpha_2^2}$$

- The Similarity function is given by:

$$Sim(I(F_{mi}), I(T'_i(M'_i))) = \frac{\|I(F_{mi}) - I(T'_i(M'_i))\|^2}{2}$$

- The Regularization term is given by:

$$Reg(T'_i) = \|\nabla(T'_i)\|^2$$

Inter-Patch Regularization

- Inter-Patch Regularization ensures the smoothness and the continuity of the transformation field across the patch boundaries
- The inter-patch regularization is achieved by composite transformation which is a distance weighted average of the two transformation fields under consideration
- The composite transformation of two adjacent patches M''_i (resulting from demons transformation on patch M'_i) and M''_j (resulting from demons transformation on patch M'_j) for their corresponding nonrigid transformation T'_i and T'_j is given by:

$$T'_p = \frac{\frac{1}{d''_{ip}} T'_{ip} + \frac{1}{d''_{jp}} T'_{jp}}{\frac{1}{d''_{ip}} + \frac{1}{d''_{jp}}}$$

$$p \in (M''_i \cap M''_j)$$

d''_{ip} = The distance of the p th pixel from the centroid of the patch M''_i
 d''_{jp} = The distance of the p th pixel from the centroid of the patch M''_j

EXPERIMENTAL RESULTS

- Experimented with four multi-view confocal 3D datasets of 72 hpf zebrafish larvae generated using standard protocols for ViBE-Z sample preparation
- The reference image and the floating image are divided into 125 volumetric patches with dimensions 200 X 140 X 140 having an overlap of 50 pixels on each side
- Registration performance is measured using Structural SIMilarity index (SSIM) and Peak Signal to Noise Ratio (PSNR). SSIM can capture local variations between two images whereas PSNR can capture global differences
- We have compared our result with that of VibeZ and we have also done an internal comparison by replacing bipartite graph matching with a greedy approach and by removing inter patch regularization

ACCURACY OF DIFFERENT ALGORITHMS

- Comparison of performance with VibeZ

SSIM-Ours	SSIM-VibeZ	PSNR-Ours	PSNR-VibeZ
0.7489	0.7418	20.0175	19.9382
0.7330	0.6315	22.7760	19.7279
0.7554	0.7388	21.7560	21.3490
0.7534	0.7427	19.0902	18.9961

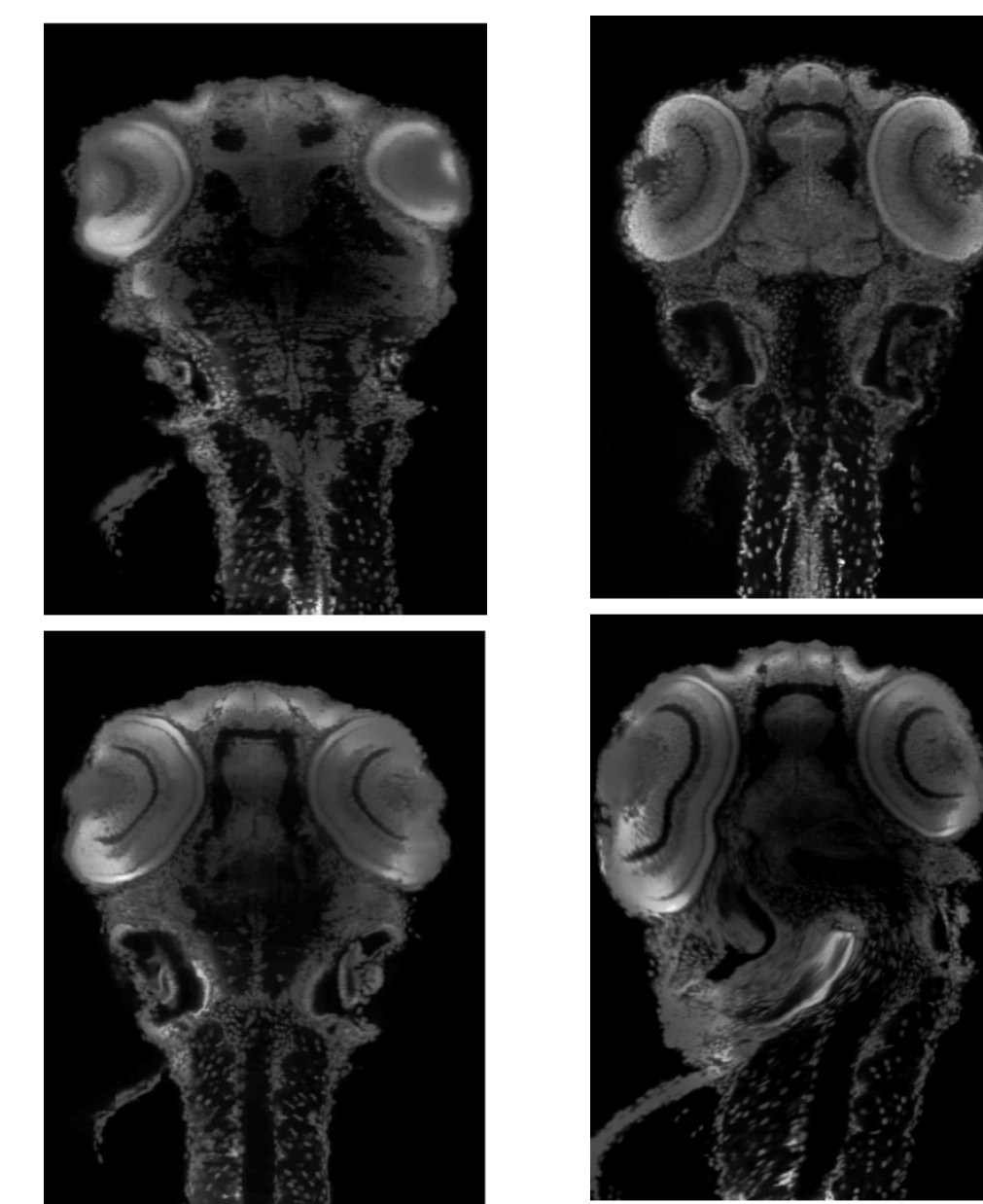


Fig. 1. Top Left: Moving Image, Top Right: Fixed Image, Bottom Left: Registration using our method, Bottom Right: Registration using VibeZ. All implementations are done in 3D and all results are shown for the same 2D slice of dataset 2.

- Internal Comparisons:

- Greedy Correspondence(GC):

SSIM-Ours	SSIM-GC	PSNR-Ours	PSNR-GC
0.7489	0.6894	20.0175	19.1551
0.7330	0.6894	22.7760	21.6930
0.7554	0.71	21.7560	21.037
0.7534	0.6897	19.0902	18.883

- No Inter Patch Regularization(NIPR):

SSIM-Ours	SSIM-NIPR	PSNR-Ours	PSNR-NIPR
0.7489	0.6894	20.0175	19.6899
0.7330	0.7277	22.7760	22.446
0.7554	0.7531	21.7560	21.6386
0.7534	0.7473	19.0902	19.0206

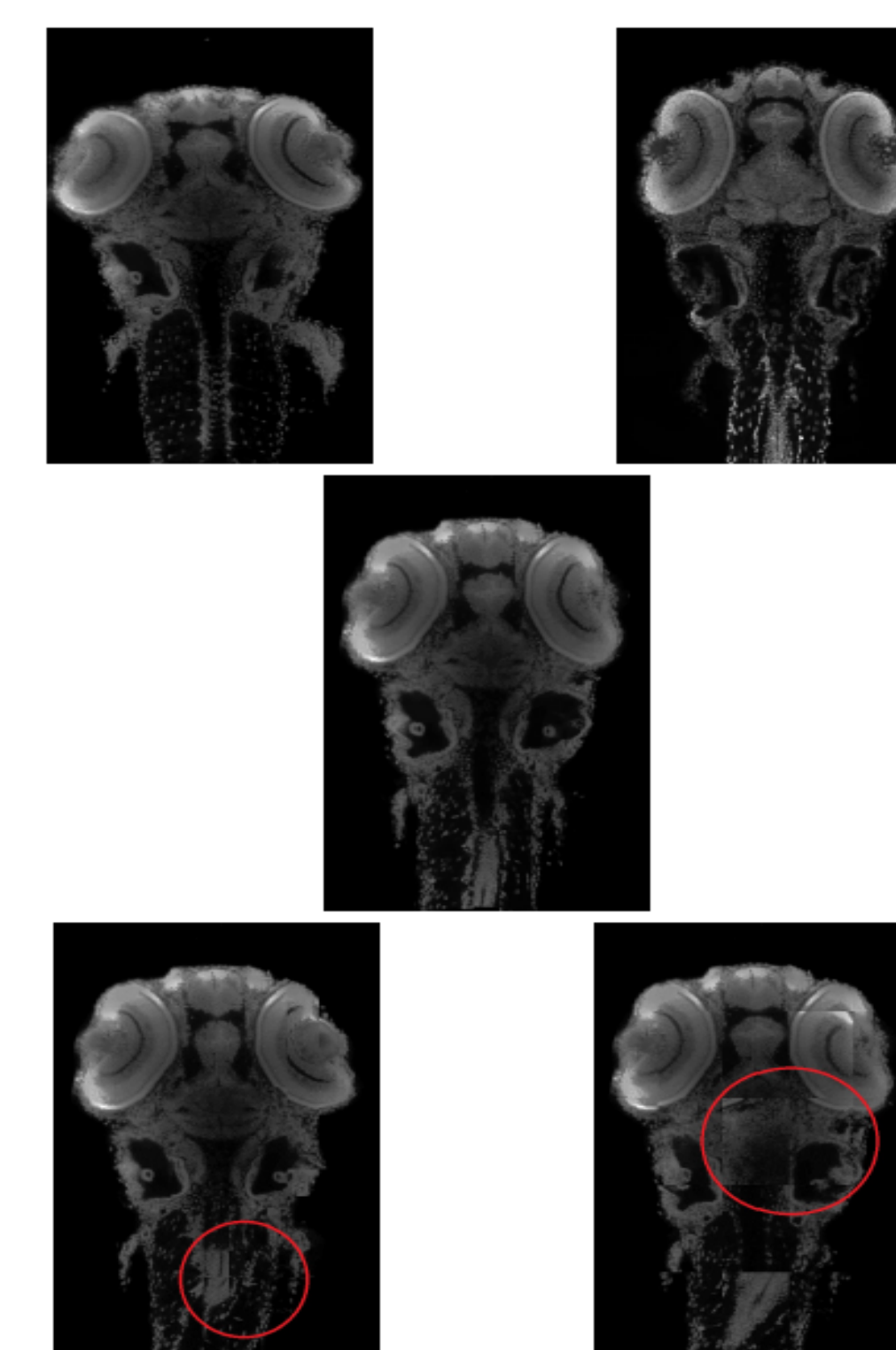


Fig2: First Row: Moving Image (left), Fixed Image (right); Second Row: Registration using our method; Third Row: Registration using our method without bipartite matching (left), Registration using our method without inter-patch regularization (right). Red circles indicate distortions. All implementations are done in 3D and all results are shown for the same 2D slice of dataset 3.

Conclusion And Future Work

- A novel non-rigid registration algorithm for zebrafish larval images yielding better accuracy
- In future, we plan to embed geometric information in the solution pipeline